Seventh Semester B.E. Degree Examination, July/August 2022 **Control Engineering**

Time: 3 hrs.

Max. Marks: 100

Note: 1. Answer any FIVE full questions, choosing ONE full question from each module. 2. Draw neat sketches, wherever required.

Module-1

Explain the closed loop control system with an example and block diagram. 1

(05 Marks)

b. Explain the requirements of an ideal control system (any five).

(05 Marks)

Explain the following controllers: (i) PI controller (ii) PID controller.

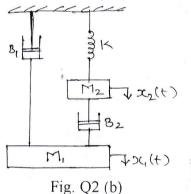
(10 Marks)

OR

2 Obtain the transfer function for an Armature Controlled DC motor. a.

(10 Marks) (10 Marks)

Obtain the transfer function for the mechanical system shown in Fig. Q2 (b).



Module-2

- Analyze the first order electrical system when it is subjected to an unit step input. (08 Marks)
 - A second order system is given by, $\frac{C(s)}{R(s)} = \frac{20}{s^2 + 6s + 25}$. Find the following transient response specifications, (i) Rise time (ii) Delay time (iii) Peak time (iv) Peak overshoot

(v) Settling time.

Also find the expression for the output response C(t) when subjected to unit step response.

(12 Marks)

For an unity feed back system with $G(s) = \frac{K}{s^2(s+3)(s+4)}$, find the value of K for which the

steady state error is to be limited to 10, when the input is $1+12t+\frac{50}{2}t^2$.

(08 Marks)

Derive an expression for a second order sender damped system which is subjected to unit step response. (12 Marks)

2. Any revealing of identification, appeal to evaluator and /or equations written eg, 42+8 = 50, will be treated as malpractice. important Note: 1. On completing your answers, compulsorily draw diagonal cross lines on the remaining blank pages.

Module-3

5 a. Reduce the block diagram by reduction technique and find $\frac{C(s)}{R(s)}$ shown in Fig. Q5 (a).

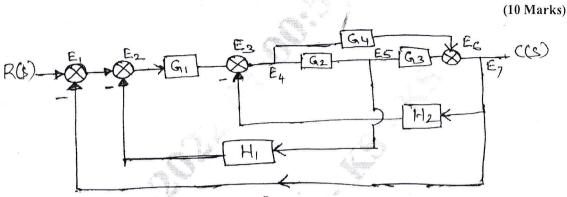
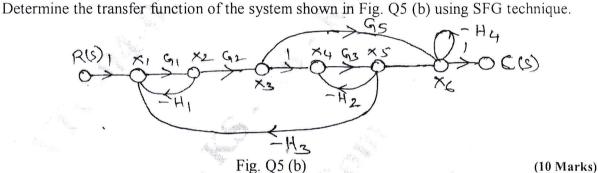


Fig. Q5 (a)



OR

- 6 a. Define the following terms:
 - (i) State
 - (ii) State variables
 - (iii) State vector.
 - (iv) State space
 - (v) State trajectory

(05 Marks)

b. Determine the state controllability and observability of the system using Kalman's test.

$$\dot{\mathbf{X}} = \begin{vmatrix} -3 & 1 & 1 \\ -1 & 0 & 1 \\ 0 & 0 & 1 \end{vmatrix} \mathbf{X} + \begin{vmatrix} 0 & 1 \\ 0 & 0 \\ 2 & 1 \end{vmatrix} \mathbf{u}, \quad \mathbf{Y} = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix} \mathbf{x}$$
 (10 Marks)

c. Evaluate the observability of the system by Gilbert's method.

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & -2 & -3 \end{bmatrix}, B = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \text{ and } C = \begin{bmatrix} 3 & 4 & 1 \end{bmatrix}.$$
 (05 Marks)

Module-4

Sketch the root locus for the given transfer function with $G(s)H(s) = \frac{K}{s(s+2)(s+4)(s+6)}$.

Comment on the stability of the system.

(20 Marks)

a. A system oscillates with a frequency ω , if it has poles of $s = \pm j\omega$ and no poles in the right half of S plane, determine the value of 'K' and 'a', so that the system shown in Fig. Q8 (a) oscillates at a frequency of 2 rad/s.

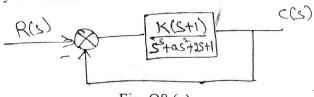


Fig. Q8 (a)

b. Sketch the root locus with $G(s)H(s) = \frac{\kappa}{s(s^2 + 4s + 10)}$. Comment on the stability. (14 Marks)

Module-5

- What are Polar Plots? Sketch the Polar Plot with $G(s)H(s) = \frac{1}{s(1+T_1s)(1+T_2s)}$.
 - b. Draw the Nyquist plot for $G(s)H(s) = \frac{K}{s^4 + 8s^3 + 17s^2 + 10s}$ and find the value of K.

(14 Marks)

Sketch the Bode plot for the system with $G(s)H(s) = \frac{2(s+0.25)}{s^2(1+s)(s+0.5)}$. From the plot 10 determine, (i) Phase cross over frequency (ii) gain cross over frequency (iii) Gain margin (iv) Phase margin. Comment on the stability of the system. (20 Marks)

GBCS SCHEME

Seventh Semester B.E. Degree Examination, July/August 2022 **Additive Manufacturing**

	Tir	ne: í	3 hrs.	ax. Marks: 100
	Note: Answer any FIVE full questions, choosing ONE full question from each module.			
 On completing your answers, compulsorily draw diagonal cross lines on the remaining blank pages. Any revealing of identification, appeal to evaluator and /or equations written eg, 42+8 = 50, will be treated as malpractice. 	1	a. b.	Module-1 What is Additive Manufacturing? Explain the need of AM. Distinguish between Additive Manufacturing and CNC Machining.	(10 Marks) (10 Marks)
	2	a. b.	OR Explain briefly generic step in Additive Manufacturing Process. Write notes on: (i) Use of layers (ii) Hybrid Manufacturing	(10 Marks) (10 Marks)
	3	a. b.	Module-2 With neat sketch, explain the working of stereolithography process. Also list disadvantages of stereolithography. Differentiate between Selective Laser Sintering and Electron Beam Meltin Fusion.	(12 Marks)
ss lines on the re aations written e	4	a. b.	OR With neat sketch, explain the working of FDM process. Briefly explain process benefits and drawbacks of PBF and FDM.	(10 Marks) (10 Marks)
raw diagonal cro uator and /or equ	5	a. b.	Module-3 Explain material jetting process with neat sketch. With schematic, explain ultrasonic consolidation. List the process parameter consolidation.	(10 Marks) ters of ultrasonic (10 Marks)
mpulsorily di ıppeal to eval	6	a. b.	OR Briefly explain process parameters of Beam Deposition Process. Write notes on: (i) Ink-Based Direct Write (ii) Thermal Spray Direct Write	(06 Marks) e (14 Marks)
answers, co	7	a. b.	Module-4 With flow chart, explain Direct Digital Manufacturing for preliminary select Explain briefly typical problems that occur in bas STL file.	tion. (10 Marks) (10 Marks)
Important Note : 1. On completing your 2. Any revealing of ide	8	a. b.	OR Classify support material and explain briefly. Write notes on: (i) STL file manipulation	(10 Marks)
	9	a. b.	(ii) Property enhancement using thermal technique in post processing Module-5 Briefly explain process multiple material processes and blended multiple material briefly the applications of additive manufacturing.	(10 Marks) aterial processes. (10 Marks) (10 Marks)
Imp	10	a. b.	OR What are the contrast between rapid prototyping and direct digital manufactors. Briefly discuss on: (i) Life-cycle costing (ii) DDM Drivers	